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## Alliance Check Toolkit

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**system-message**

**ERROR/3** in README.rst, line 4

Duplicate substitution definition name: "Verilog". backrefs:

**system-message**

**ERROR/3** in README.rst, line 9

Duplicate substitution definition name: "DRC". backrefs:

**system-message**

**ERROR/3** in README.rst, line 78

Duplicate substitution definition name: "blif". backrefs:

## Toolkit Purpose

This toolkit has been created to allow developers to share through **git** a set of benchmarks to validate their changes in Alliance & Coriolis before committing and pushing them in their central repositories. A change will be considered as validated when all the developers can run successfully all the benches in their respective environments.

As a consequence, this repository is likely to be *very* unstable and the commits not well documented as they will be quick corrections made by the developers.

## Release Notes

### August 30, 2019

Katana is now used as the default router. It can now manage a complete chip design with I/O pads. As a consequence, the **Makefile** are all modified, the variable `USE_KATANA=Yes` is changed to `USE_KITE=No` (see [Benchmark Makefiles](#)).

Designs with I/O pads are also modified to be processed by Katana as it uses a different approach.

## Toolkit Contents

The toolkit provides:

- **OK Status.** A set of eight benchmark designs that are used as regression tests (see [go.sh](#)). Benchmarks with multiple target technologies still count as one.
- **KO Status.** Examples that currently fails due to incomplete or poorly implemented features of Coriolis.
- **Unchecked.** Non-fonctional examples, or really too long to run for a regression test.

Design	Technology	Cell Libraries	Status
adder	mosis	nsxlib, mpplib, msplib	Unchecked
am2901 (standard cells)	Symbolic cmos	sxlib, pxlib	OK
am2901 (datapath)	Symbolic cmos	sxlib, dp_sxlib, pxlib	OK
alliance-run (am2901)	Symbolic cmos	sxlib, dp_sxlib, padlib	Unchecked
RingOscillator	Symbolic cmos	sxlib	OK
cpu	mosis	nsxlib, mpplib, msplib	OK
<b>SNX</b>			
snx / Alliance	Symbolic cmos	sclib	Unchecked
snx / sxlib2M	Symbolic cmos 2M	sxlib	OK
snx / cmos	Symbolic cmos	sxlib, pxlib	OK
snx / cmos45	Symbolic cmos 45	nsxlib, mpplib	OK
snx / FreePDK_45	FreePDK 45	gsc145	OK
snx / c35b4	AMS 350nm c35b4	corelib	KO
<b>6502</b>			
6502 / cmos45	Symbolic cmos 45	nsxlib	OK
Arlet6502 / cmos350	Symbolic cmos 45	nsxlib	OK
<b>MIPS</b>			
mips (microprogrammed)	Symbolic cmos	sxlib, dp_sxlib, rf2lib	OK
mips (pipeline)	Symbolic cmos	sxlib, dp_sxlib, rf2lib	OK
mips (pipeline+chip)	Symbolic cmos	sxlib, dp_sxlib, rf2lib, pxlib	Unchecked
<b>Miscellaneous</b>			
fpga (Moc4x4_L4C12)	Symbolic cmos	sxlib	KO
ispd05 (bigblue1)	None	Generated on the fly	Unchecked
ARMv2a	Symbolic cmos	sxlib, pxlib	OK
<b>Vex RISC-V</b>			
VexRiscV / cmos	Symbolic cmos	sxlib, pxlib	OK
VexRiscV / cmos45	Symbolic cmos 45	nsxlib, mpplib	OK
VexRiscV / FreePDK_45	FreePDK 45	gsc145	KO
VexRiscV / c35b4	AMS 350nm c35b4	corelib	KO
<b>nMigen basic ALU example</b>			
alu / scn6m_deep_09	mosis	nsxlib	Unchecked

- The nMigen design is the basic alu taken from the distribution to perform integration test in the design flow. The target technology is the mosis 180nm (`scn6m_deep`).
- The Arlet6502 is taken from [Arlet's MOS 6502 core](#) and is routed using the four metal symbolic technology (so the router has three available).
- Three cell libraries.

All those libraries are for use with mosis and FreePDK45 technologies. We provides them as part of the toolkit as we are still in the process of validating that technology, and we may have to perform quick fixes on them. The design are configured to use them instead of those supplied by the Alliance installation.

1. `nsxlib`: Standard Cell library, compliant with mosis.
2. `mpxlib`: Pad library, compliant with Coriolis.
3. `msplib`: Pad library, compliant with Alliance / `ring`. Cells in this library are *wrappers* around their counterpart in `mpxlib`, they provides an outer layout shell that is usable by `ring`.

- The rds files for mosis (`scn6m_deep_09.rds`) and FreePDK45 technologies, for the same reason as the cell libraries.
- Miscellenous helper scripts.

## Toolkit Layout

The files are organized as follow :

Directory	Contents
<code>./etc/</code>	Configuration files
<code>./etc/mk/</code>	Makefiles rules to build benchmarks. This directory must be symbolic linked into each benchmark directory
<code>./etc/mk/users.d/</code>	Directory holding the configuration for each user
<code>./bin/</code>	Additional scripts
<code>./cells/&lt;LIBDIR&gt;</code>	Standard cells libraries.
<code>./benchs/&lt;BENCH&gt;/&lt;techno&gt;/</code>	Benchmark directories
<code>./doc/</code>	This documentation directory

## Benchmark Makefiles

A benchmark **Makefile** is build by setting up variables `USE_<FEATURE>=Yes/No` then including the set of rules `./mk/design-flow.mk`. The directory `alliance-check-toolkit/etc/mk/` must be symlinked in the directory where the **Makefile** resides.

The **Makefile** provides some or all of the following targets. If the place and route stage of a benchmark has multiple target technology, one directory is created for each.

Coriolis	<code>blif</code>	Synthetize the netlist with <code>Yosys</code> .
	<code>layout</code>	The complete symbolic layout of the design (P&R).
	<code>gds</code>	Generate the real layout (gdsii)
	<code>drc</code>	Symbolic layout checking
	<code>lvx</code>	Perform lvs.
	<code>graal</code>	Launch <code>graal</code> in the <b>Makefile</b> 's environnement
	<code>dreal</code>	Launch <code>dreal</code> in the <b>Makefile</b> 's environnement, and load the <code>gds</code> file of the design.
	<code>view</code>	Launch <code>cgf</code> and load the design (chip)
	<code>cgf</code>	Launch <code>cgf</code> in the <b>Makefile</b> 's environnement

A top **Makefile** in a bench directory must looks like:

```

LOGICAL SYNTHESIS = Yosys
PHYSICAL SYNTHESIS = Coriolis
DESIGN_KIT = nsxlib45

USE_CLOCKTREE = No
USE_DEBUG = No
USE_KITE = No

NETLISTS = VexRiscv

include ./mk/design-flow.mk

blif:    VexRiscv.blif
layout: vexriscv_r.ap
gds:    vexriscv_r.gds

lvx:    lvx-vst-vexriscv
drc:    drc-vexriscv_r

```

Where variables have the following meaning:

Variable	Usage
LOGICAL_SYNTHESIS	Tells what synthesis tool to use between Alliance or Yosys. Netlists must be pre-generated if this variable is empty or not present
PHYSICAL_SYNTHESIS	Tells what place & route tools to use between Alliance (i.e. ocp, nero & ring) and Coriolis
DESIGN_KIT	The target technology and the standard cell libraries to use, for the supported values see below.
NETLISTS	The list of <i>netlists</i> that are requireds to perform the place and route stage. See the complete explanation below
VST_FLAGS	Flags to be passed to the tools driving <b>vst</b> files. Due to some non-standard syntax in the Alliance format, if you have a hierarchical design, please set it to <code>--vst-use-concat</code>
USE_CLOCKTREE	Adds a clock-tree to the design (Coriolis)
USE_DEBUG	Use the debugger enabled version of <b>cgt</b>
USE_KITE	Use the old Kite (digital only) router

Detailed semantic of the NETLISTS variable:

- Netlists name must be given without file extensions. Those are guessed according to the selected synthesis tool.
- According to the value of LOGICAL\_SYNTHESIS they are user supplied or generated. In the later case, be aware that calling the `clean` target will remove the generated files.
- In case the logical synthesis stage is needed, the file holding the behavioral description is the *first* of the item list. In certain contexts, it will also be considered as the chip's core.
- If the behavioral description is hierarchical, each sub model must be added to the NETLISTS variable (*after* the top level one). In case of Yosys synthesis, `blif2vst.py` will generate a **vst** file for each model of the hierarchy. We add them to the list so a `make clean` will remove not only the top level **vst** (and associated **ap** after placement), but the whole hierarchy.

A slightly more complex example is below. The behavioral description that will be synthesised must be in `alu_hier` (in fact `alu_hier.il` or `alu_hier.v` as we are using Yosys). Two sub-model are generated by the synthesis, `add` and `sub`, so we add them in tail of the NETLISTS variable.

```

LOGICAL_SYNTHESIS = Yosys
PHYSICAL_SYNTHESIS = Coriolis
DESIGN_KIT = nsxlib

YOSYS_FLATTEN = No
VST_FLAGS = --vst-use-concat
USE_CLOCKTREE = No
USE_DEBUG = No
USE_KITE = No

NETLISTS = alu_hier \
            add      \
            sub

```

```
include ./mk/design-flow.mk

blif:      alu_hier.blif
vst:      alu_hier.vst
layout:   alu_hier_r.ap
gds:      alu_hier_r.gds

lvx:      lvx-alu_hier_r
druc:     druc-alu_hier_r
view:     cgt-alu_hier_r
graal:    graal-alu_hier_r
```

Available design kits (to set `DESIGN_KIT`):

Value	Design kit
sxlib	The default Alliance symbolic technology. Use the <code>sxlib</code> and <code>pxlib</code> libraries.
nsxlib	Symbolic technology fitted for mosis 180nm, 6 metal layers <code>scn6m_deep</code>
nsxlib45	The symbolic technology fitted for 180nm and below. Used for FreePDK45 in symbolic mode.
FreePDK_45	Direct use of the real technology FreePDK45.
c35b4	AMS 350nm c35b4 real technology.



## Setting Up the User's Environment

Before running the benchmarks, you must create a configuration file to tell where all the softwares are installed. The file is to be created in the directory:

```
alliance-check-toolkit/etc/mk/users.d/
```

The file itself must be named from your username, if mine is `jpc`:

```
alliance-check-toolkit/etc/mk/users.d/user-jpc.mk
```

Example of file contents:

```
# Where Jean-Paul Chaput gets his tools installed.

export NDA_TOP          = ${HOME}/crypted/soc/techno
export AMS_C35B4        = ${NDA_TOP}/AMS/035hv-4.10
export FreePDK_45       = ${HOME}/coriolis-2.x/work/DKs/FreePDK45
export CORIOLIS_TOP     = $(HOME)/coriolis-2.x/$(BUILD_VARIANT)$(LIB_SUFFIX_)/$(BUI
export ALLIANCE_TOP     = $(HOME)/alliance/$(BUILD_VARIANT)$(LIB_SUFFIX_)/install
export CHECK_TOOLKIT    = $(HOME)/coriolis-2.x/src/alliance-check-toolkit
export AVERTEC_TOP      = /dsk/l1/tasyag/Linux.el7_64/install
export YOSYS_TOP        = /usr
```

All the variable names and values are more or less self explanatory...

## CORIOLIS Configuration Files

Unlike Alliance which is entirely configured through environment variables or system-wide configuration file, Coriolis uses configuration files in the current directory. They are present for each bench:

- `<cwd>/coriolis2/__init__.py` : Just to tell Python that this directory contains a module and be able to *import* it.
- `<cwd>/coriolis2/settings.py` : Override system configuration, and setup technology.

## CORIOLIS and Clock Tree Generation

When Coriolis is used, it create a clock tree which modificate the original netlist. The new netlist, with a clock tree, has a postfix of `_clocked`.



### Note

**Trans-hierarchical Clock-Tree.** As CORIOLIS do not flatten the designs it creates, not only the top-level netlist is modiflicated. All the sub-blocks connected to the master clock are also duplicated, with the relevant part of the clock-tree included.

## RHEL6 and Clones

Under rhel6 the developpement version of Coriolis needs the `devtoolset-2.os.mk` tries, based on `uname` to switch it on or off.

## Yosys Wrapper Script `yosys.py`

As far as I understand, `yosys` do not allow it's scripts to be parametrised. The `yosys.py` script is a simple wrapper around `yosys` that generate a custom tailored tcl script then call `yosys` itself. It can manage two input file formats, Verilog and rtlil and produce a `blif` netlist.

```
ego@home:VexRiscv/cmos350$ ../../../../bin/yosys.py \
--input-lang=Verilog \
--design=VexRiscv \
--top=VexRiscv \
--liberty=../../../../cells/nsxlib/nsxlib.lib
```

Here is an example of generated tcl script: `VexRiscv.ys`:

```
set verilog_file VexRiscv.v
set verilog_top VexRiscv
set liberty_file ../alliance-check-toolkit/cells/nsxlib/nsxlib.lib
yosys read_verilog $verilog_file
yosys hierarchy -check -top $verilog_top
yosys synth -top $verilog_top
yosys dfflibmap -liberty $liberty_file
yosys abc -liberty $liberty_file
yosys clean
yosys write_blif VexRiscv.blif
```

## Benchmarks Special Notes

### `alliance-run`

This benchmark comes mostly with it's own rules and do not uses the ones supplied by `rules.mk`. It uses only the top-level configuration variables.

It a slightly modified copy of the `alliance-run` found in the Alliance package (modification are all in the **Makefile**). It build an am2901, but it is splitted in a control and an operative part (data-path). This is to also check the data-path features of Alliance.

And lastly, it provides a check for the Coriolis encapsulation of Alliance through Python wrappers. The support is still incomplete and should be used only by very experienced users. See the `demo*` rules.

### AM2901 standard cells

This benchmark can be run in loop to check slight variations. The clock tree generator modify the netlist trans-hierarchically then saves the new netlist. But, when there's a block *without* a clock (say an alu for instance) it is not modified yet saved. So the `vst` file got rewritten. And while the netlist is rewritten in a deterministic way (from how it was parsed), it is *not* done the same way due to instance and terminal re-ordering. So, from run to run, we get identical netlists but different files inducing slight variations in how the design is placed and routed. We use this *defect* to generate deterministic series of random variation that helps check the router. All runs are saved in a `./runs` sub-directory.

The script to perform a serie of run is `./doRun.sh`.

To reset the serie to a specific run (for debug), you may use `./setRun.sh`.

## Libraries Makefiles



### Note

For those part to work, you need to get `hitas` & `yagle`:  
[HiTas -- Static Timing Analyser](#)

The `bench/etc/mk/check-library.mk` provides rules to perform the check of a library as a whole or cell by cell. To avoid too much clutter in the library directory, all the intermediate files generated by the verification tools are kept in a `./check/` subdirectory. Once a cell has been validated, a `./check/<cell>.ok` is generated too prevent it to be checked again in subsequent run. If you want to force the recheck of the cell, do not forget to remove this file.

### Checking Procedure

- DRC with `druc`.
- Formal proof between the layout and the behavioral description. This is a somewhat long chain of tools:
  1. `cougar`, extract the spice netlist (`.spi`).
  2. `yagle`, rebuild a behavioral description (`.vhd`) from the spice netlist.
  3. `vasy`, convert the `.vhd` into a `.vbe` (Alliance vhdl subset for behavioral descriptions).
  4. `proof`, perform the formal proof between the reference `.vbe` and the extracted one.

Rule or File	Action
<code>check-lib</code>	Validate every cell of the library
<code>clean-lib-tmp</code>	Remove all intermediate files in the <code>./check</code> subdirectory <b>except</b> for the <code>*.ok</code> ones. That is, cells validated will not be rechecked.
<code>clean-lib</code>	Remove all files in <code>./check</code> , including <code>*.ok</code>
<code>./check/&lt;cell&gt;.ok</code>	Use this rule to perform the individual check of <code>&lt;cell&gt;</code> . If the cell is validated, a file of the same name will be created, preventing the cell to be checked again.

### Synopsys Liberty .lib Generation

The generation of the liberty file is only half-automated. `hitas` / `yagle` build the base file, then we manually perform the two modifications (see below).

The rule to call to generate the liberty file is: `<libname>-dot-lib` where `<libname>` is the name of the library. To avoid erasing the previous one (and presumably hand patched), this rule create a `<libname>.lib.new`.

1. Run the `./bin/cellsArea.py` script which will setup the areas of the cells (in square um). Work on `<libname>.lib.new`.
2. For the synchronous flip-flop, add the functional description to their timing descriptions:

```
cell (sff1_x4) {
  pin (ck) {
    direction : input ;
    clock : true ;
    /* Timing informations ... */
  }
  pin (q) {
```

```

        direction : output ;
        function : "IQ" ;
        /* Timing informations ... */
    }
    ff(IQ,IQN) {
        next_state : "i" ;
        clocked_on : "ck" ;
    }
}

cell (sff2_x4) {
    pin (ck) {
        direction : input ;
        clock : true ;
        /* Timing informations ... */
    }
    pin (q) {
        direction : output ;
        function : "IQ" ;
        /* Timing informations ... */
    }
    ff(IQ,IQN) {
        next_state : "(cmd * i1) + (cmd' * i0)" ;
        clocked_on : "ck" ;
    }
}

```



#### Note

The tristate cells **ts\_** and **nts\_** are not included in the `.lib`.

## Helpers Scripts

tcl scripts for `avt_shell` related to cell validation and characterization, in `./benchs/bin`, are:

- `extractCell.tcl`, read a spice file and generate a vhdl behavioral description (using `yagle`). This file needs to be processed further by `vasy` to become an Alliance behavioral file (`vbe`). It takes two arguments: the technology file and the cell spice file. Cell which name starts by `sff` will be treated as D flip-flop.
- `buildLib.tcl`, process all cells in a directory to build a liberty file. Takes two arguments, the technology file and the name of the liberty file to generate. The collection of characterized cells will be determined by the `.spi` files found in the current directory.

## Macro-Blocks Makefiles

The `bench/etc/mk/check-generator.mk` provides rules to perform the check of a macro block generator. As one library cell may be used to build multiple macro-blocks, one **Makefile** per macro must be provided. The `dot` extension of a **Makefile** is expected to be the name of the macro-block. Here is a small example for the register file generator, `Makefile.block_rf2`:

```

        TK_TOP = ../..
export      MBK_CATA_LIB = $(TOOLKIT_CELLS_TOP)/nrf2lib

    include $(TK_TOP)/etc/mk/alliance.mk
    include $(TK_TOP)/etc/mk/mosis.mk

```

```
include $(TK_RTOP)/etc/mk/check-generator.mk

check-gen: ./check/block_rf2_p_b_4_p_w_6.ok \
           ./check/block_rf2_p_b_2_p_w_32.ok \
           ./check/block_rf2_p_b_64_p_w_6.ok \
           ./check/block_rf2_p_b_16_p_w_32.ok \
           ./check/block_rf2_p_b_32_p_w_32.ok
```

**Note**

In the `check-gen` rule, the name of the block **must** match the `.dot` extension of the **Makefile**, here: `block_rf2`.

Macro-block generators are parametrized. We use a special naming convention to pass parameters names and values through the rule name. To declare a parameter, add `_p_`, then the name of the parameter and its value separated by a `_`.

String in Rule Name	Call to the generator
<code>_p_b_16_p_w_32</code>	<code>-b 16 -w 32</code>

When multiple flavors of a generator could be built upon the same cell library, one **Makefile** per flavor is provided. To run them all at once, a `makeAll.sh` script is also available.

The `check-gen` rule only performs a drc and a lvs to check that their router has correctly connected the cells of a macro-block. It doesn't perform any functional verification.

To perform a functional abstraction with `yagle` you may use the following command:

```
ego@home:nrf2lib> make -f Makefile.block_rf2 block_rf2_b_4_p_w_6_kite.vhd
```

Even if the resulting vhd cannot be used it is always good to look in the report file `block_rf2_b_4_p_w_6_kite` for any error or warning, particularly any disconnected transistor.

## Calling the Generator

A script `./check/generator.py` must be written in order to call the generator in standalone mode. This script is quite straightforward, what changes between generators is the command line options and the `stratus.buildModel()` call.

After the generator call, we get a netlist and placement, but it is not finished until it is routed with the Coriolis router.

**Note**

Currently all macro-block generators are part of the STRATUS netlist capture language tool from CORIOLIS.

## Scaling the Cell Library

This operation has to be done once, when the cell library is initially ported. The result is put in the **git** repository, so there's no need to run it again on a provided library.

The script is `./check/scaleCell.py`. It is very sensitive on the way the library paths are set in `.coriolis2/settings.py`. It must have the target cell library setup as the `WORKING_LIBRARY` and the source cell library in the `SYSTEM_LIBRARY`. The technology must be set to the target one. And, of course, the script must be run in the directory where `.coriolis2/` is located.

The heart of the script is the `scaleCell()` function, which works on the original cell in variable `sourceCell` (argument) and `scaledCell`, the converted one. Although the script is configured to use the *scaled* technology, this does not affect the values of the coordinates of the cells we read, whatever their origin. This means that when we read the `sourceCell`, the coordinates

of its components keeps the value they have under `SxLib`. It is *when* we duplicate them into the `scaledCell` that we perform the scaling (i.e. multiply by two) and do whatever adjustments we need. So when we have an adjustment to do on a specific segment, say slightly shift a `NDIF`, the coordinates must be expressed as in `SxLib` (once more: *before* scaling).

**Note**

There is a safety in `./check/scaleCell.py`, it will not run until the target library has not been emptied of its cells.

The script contains a `getDeltas()` function which provide a table on how to resize some layers (width and extension).

As the scaling operations is very specific to each macro-block, this script is *not* shared, but customized for each one.

## Tools & Scripts

### One script to run them all: `go.sh`

To call all the bench's `Makefile` sequentially and execute one or more rules on each, the small script utility `go.sh` is available. Here are some examples:

```
ego@home:bench$ ./bin/go.sh clean
ego@home:bench$ ./bin/go.sh lvx
```

### Command Line `cgt`: `doChip.py`

As a alternative to `cgt`, the small helper script `doChip.py` allows to perform all the P&R tasks, on an stand-alone block or a whole chip.

### Blif Netlist Converter

The `blif2vst.py` script convert a `.blif` netlist into an Alliance one (`vst`). This is a very straightforward encapsulation of Coriolis. It could have been included in `doChip.py`, but then the `make` rules would have been much more complicated.

### Pad Layout Converter `px2mpx.py`

The `px2mpx.py` script convert pad layout from the `pxlib` (Alliance dummy technology) into `mpxlib` (mosis compliant symbolic technology).

Basically it multiplies all the coordinate by two as the source technology is  $1\mu$  type and the target one a  $2\mu$ . In addition it performs some adjustment on the wire extension and minimal width and the blockage sizes.

As it is a one time script, it is heavily hardwired, so before using it do not forget to edit it to suit your needs.

The whole conversion process is quite tricky as we are cheating with the normal use of the software. The steps are as follow:

1. Using the Alliance dummy technology and in an empty directory, run the script. The layouts of the converted pads (`*_mpx.ap`) will be created.
2. In a second directory, this time configured for the mosis technology (see `.coriolis2 techno.conf`) copy the converted layouts. In addition to the layouts, this directory **must also contain** the behavioral description of the pads (`.vbe`). Otherwise, you will not be able to see the proper layout.
3. When you are satisfied with the new layout of the pads, you can copy them back in the official pad cell library.

**Note**

**How Coriolis Load Cells.** Unlike in ALLIANCE, CORIOLIS maintain a much tighter relationship between physical and logical (structural or behavioral) views. The loading process of a cell try *first* to load the logical view, and if found, keep tab of the directory it was in. *Second* it tries to load the physical view from the same directory the logical view was in. If no logical view is found, only the physical is loaded.

Conversely, when saving a cell, the directory it was loaded from is kept, so that the cell will be overwritten, and not duplicated in the working directory as it was in ALLIANCE.

This explains why the behavioral view of the pad is needed in the directory the layouts are put into. Otherwise you would only see the pads of the system library (if any).

## Cadence Support

To perform comparisons with Cadence edi tools (i.e. `encounter` NanoRoute), some benchmarks have a sub-directory `encounter` holding all the necessary files. Here is an example for the design named `<fpga>`.

encounter directory	
File Name	Contents
<code>fpga_export.lef</code>	Technology & standard cells for the design
<code>fpga_export.def</code>	The design itself, flattened to the standard cells.
<code>fpga_nano.def</code>	The placed and routed result.
<code>fpga.tcl</code>	The tcl script to be run by <code>encounter</code>

The LEF/DEF file exported or imported by Coriolis are *not* true physical files. They are pseudo-real, in the sense that all the dimensions are directly taken from the symbolic with the simple rule `1 lambda = 1 micron`.

**Note**

**LEF/DEF files:** Coriolis is able to import/export in those formats only if it has been compiled against the Si2 relevant libraries that are subjects to specific license agreements. So in case we don't have access to those we supplies the generated LEF/DEF files.

The `encounter` directory contains the LEF/DEF files and the tcl script to be run by `encounter`:

```
ego@home:encounter> . ../../etc/EDI1324.sh
ego@home:encounter> encounter -init ./fpga.tcl
```

Example of tcl script for `encounter`:

```
set_global _enable_mmmc_by_default_flow          $CTE::mmmc_default
suppressMessage ENCEXT-2799
win
loadLefFile fpga_export.lef
loadDefFile fpga_export.def
floorPlan -site core -r 0.998676319592 0.95 0.0 0.0 0.0 0.0
getIoFlowFlag
fit
setDrawView place
setPlaceMode -fp false
placeDesign
generateTracks
generateVias
```

```
setNanoRouteMode -quiet -drouteFixAntenna 0
setNanoRouteMode -quiet -drouteStartIteration 0
setNanoRouteMode -quiet -routeTopRoutingLayer 5
setNanoRouteMode -quiet -routeBottomRoutingLayer 2
setNanoRouteMode -quiet -drouteEndIteration 0
setNanoRouteMode -quiet -routeWithTimingDriven false
setNanoRouteMode -quiet -routeWithSiDriven false
routeDesign -globalDetail
global dbgLefDefOutVersion
set dbgLefDefOutVersion 5.7
defOut -floorplan -netlist -routing fpga_nano.def
```

## Technologies

We provides configuration files for the publicly available mosis technology SCN6M\_DEEP.

- `./bench/etc/scn6m_deep_09.rds`, rds rules for symbolic to real transformation.
- `./bench/etc/scn6m_deep.hsp`, transistor spice models for yagle.

References:

- [MOSIS Scalable CMOS \(SCMOS\)](#)
- [MOSIS Wafer Acceptance Tests](#)